

SPECIAL RELATIVITY IMPORTANT RELATIONS AND DEFINITIONS

All transformations are written for the standard configuration of the primed and not primed reference frames: the primed reference frame is moving in x -direction with velocity u .

LORENTZ TRANSFORMATIONS :
the origins of the two reference frames
coincide at $t = t' = 0$

4-VECTOR TRANSFORMATIONS:

$$\left\{ \begin{array}{l} x' = \gamma(x - ut) \\ y' = y; \quad z' = z \\ t' = \gamma\left(t - \frac{u}{c^2}x\right) \end{array} \right. \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

$$\left\{ \begin{array}{l} A'_x = \gamma\left(A_x - \frac{u}{c}A_t\right) \\ A'_y = A_y; \quad A'_z = A_z \\ A'_t = \gamma\left(A_t - \frac{u}{c}A_x\right) \end{array} \right. \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

EXAMPLES OF 4-VECTORS:

$$\vec{\Delta R} \equiv [\Delta x, \Delta y, \Delta z, c\Delta t];$$

$$\vec{V} \equiv \frac{d}{d\tau}[\Delta x, \Delta y, \Delta z, c\Delta t] = \gamma(v) \cdot [v_x, v_y, v_z, c]; \quad \gamma(v) = \frac{1}{\sqrt{1 - v^2/c^2}}$$

$$\vec{K} \equiv \left[\mathbf{k}, \frac{\omega}{c} \right];$$

$$\vec{P} \equiv m\vec{V} \equiv (\vec{p}, E/c);$$

$$\vec{A} \equiv \frac{d\vec{V}}{d\tau} = \gamma \frac{d\gamma}{dt} [\vec{v}, c] + \gamma^2 [\vec{a}, 0]; \quad \gamma = \frac{1}{\sqrt{1 - v^2/c^2}}; \quad \frac{d\gamma}{dt} = \frac{v/c^2}{(1 - v^2/c^2)^{3/2}} \frac{dv}{dt};$$

$$\vec{F} \equiv \frac{d}{d\tau} \vec{P} = \gamma(v) \left[\vec{f}, \frac{1}{c} \frac{dE}{dt} \right] = \frac{dm}{d\tau} \vec{V} + m\vec{A}; \quad \gamma(v) = \frac{1}{\sqrt{1 - v^2/c^2}};$$

RELATIVISTIC TRANSFORMATIONS OF 3-VECTORS

VELOCITY TRANSFORMATIONS:

$$\left\{ \begin{array}{l} v'_1 = \frac{v_1 - u}{1 - uv_1/c^2} \\ v'_2 = \frac{1}{1 - uv_1/c^2} \cdot \frac{v_2}{\gamma} \\ v'_3 = \frac{1}{1 - uv_1/c^2} \cdot \frac{v_3}{\gamma} \end{array} \right. \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

WAVE VECTOR AND FREQUENCY TRANSFORMATIONS (PLANE WAVE):

$$\begin{cases} k'_x = \gamma \left(k_x - \frac{u}{c^2} \omega \right) \\ k'_y = k_y \\ k'_z = k_z \end{cases} \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

$$\omega' = \gamma \left(\omega + \frac{u}{v} \cos \theta \right) \omega$$

$$\tan \theta' = \frac{k'_y}{k'_x} = \frac{\sin \theta}{\gamma \left(\cos \theta + \frac{u v}{c^2} \right)}$$

$$v' = \frac{\gamma (v + u \cos \theta)}{\sqrt{\frac{\gamma^2}{c^2} (v + u \cos \theta)^2 + 1 - \frac{v^2}{c^2}}}$$

FORCE AND POWER TRANSFORMATIONS :

$$\begin{cases} f'_1 = \frac{1}{1 - v_1 u / c^2} \left(f_1 - \frac{u}{c^2} \frac{dE}{dt} \right) \\ f'_2 = \frac{1}{\gamma (1 - v_1 u / c^2)} f_2; \\ f'_3 = \frac{1}{\gamma (1 - v_1 u / c^2)} f_3 \\ \frac{dE'}{dt'} = \frac{1}{1 - v_1 u / c^2} \left(\frac{dE}{dt} - u f_1 \right) \end{cases} \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

If $\frac{dm}{d\tau} = 0$ then $\frac{dE}{dt} = \vec{\mathbf{f}} \cdot \vec{\mathbf{v}}$

EM FIELD TRANSFORMATIONS:

$$\begin{aligned} e'_x &= e_x \\ e'_y &= \gamma (e_y - u b_z) \\ e'_z &= \gamma (e_z + u b_y) \\ b'_x &= b_x \\ b'_y &= \gamma (b_y + e_z u / c^2) \\ b'_z &= \gamma (b_z - e_y u / c^2) \end{aligned} \quad \gamma = \frac{1}{\sqrt{1 - u^2/c^2}}$$

LORENTZ FORCE

$$\vec{\mathbf{f}} = q \vec{\mathbf{v}} \times \vec{\mathbf{b}} + q \vec{\mathbf{e}}$$